



Unidrive SP

Panel Mount Universal AC and Servo Drive

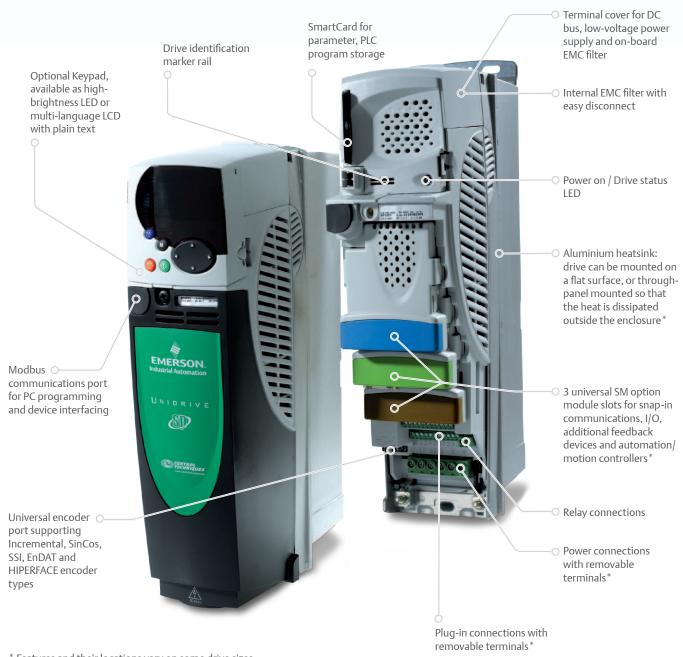
0.5 - 200hp (0.37 - 132kW) 208 - 240V / 380 - 480V / 575V / 690V





Unidrive SP, the Ultimate High Performance AC Drive

Performance and flexibility allow you to do something new — create opportunities to innovate, find better ways to control your application, increase speeds, improve processes and reduce the footprint of your system. Unidrive SP, Control Techniques' high-performance drive family, allows you to achieve this. Unidrive SP is the ultimate universal AC drive.

























One Drive, Any Power, Any Motor

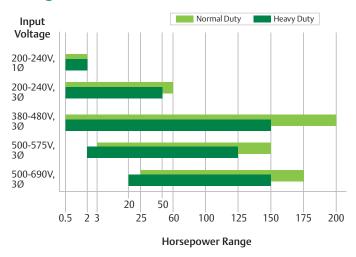
The Unidrive SP is a universal AC and Servo drive with ratings from 0.5 to 2,900hp. This versatile drive can be used to control virtually any motor with any type of feedback device and with any control scheme. These drives are packaged in three form factors: Panel Mount, Free Standing and Solution Platform Modular (SPM).

Panel Mount – Standard Drives

0.5 - 200hp (0.37kW - 132kW)

Unidrive SP Panel Mount drives are standard AC input, AC output sizes for installation within a control panel. Optional conduit boxes are available for wall mounting.

Ratings





Performance Advantage

Dual Duty Ratings — Normal and Heavy

One drive provides cost-effective sizing choices for all applications.

Universal Motor Control

Open- and closed-loop induction motor control, closed-loop servo motor control and power regeneration control in one drive.

24Vdc Auxiliary Power Supply Input

Maintains control, network communications and position loop on input AC power loss, minimizing system recovery time.

Comprehensive Auto-tune

Inertia monitoring and static auto-tune reduce startup time.

Universal Feedback Interface

Interface supports 14 different types of feedback devices, including several absolute encoders. Multiple encoders can be connected to a single drive with SM option modules.

High-resolution Analog Input

Input has 16-bit, 250 μ sec interface for high-performance applications. Two additional 10-bit analog inputs for lower level controls.

Extensive Fieldbus Connectivity

ModbusRTU (Standard), Profibus-DP (V1), Ethernet, DeviceNet, CAN, CANOpen, EtherCAT, SERCOS, Interbus-S and CTNet/CTSync are optional via zero-space SM option modules. Up to four fieldbus devices can connect to a single drive, eliminating the need for expensive gateways.

Universal Option Slots

Unidrive SP size 0 has two slots. Unidrive SP sizes 1 and up have 3 snap-in option module slots. Fieldbus, I/O and Application modules fit in any of the open SM option modular slots.

Safe Torque Off Function

Function conforms to IEC61800-5-2, SIL 3 and EN81-1 for machine safety with system cost reduction.

SmartCard for Simple Setup and Cloning

Easy-to-use card stores drive configuration for simple startup and parameter cloning. Supplied FREE with every Unidrive SP.

Keypad Options

Choose no keypad, LED keypad or LCD keypad based on the system design and operating environment.

Drive-mounted Brake Resistors

Unidrive SP sizes 0, 1 and 2 feature a drive-mounted brake resistor option to reduce panel space requirements.



Any Motor, Any Encoder

Unidrive SP provides high-performance motor control for induction motors, asynchronous servo and synchronous servo motors. The control mode is simply selected using the drive keypad.

- **Servo** Precision, dynamic control supporting a wide range of rotary and linear motors
- Closed-loop vector Ultimate precision control of induction motors offering full motor torque at zero speed
- **Rotor Flux Control (RFC) mode** Superior dynamic performance and stability without a feedback device
- **Open-loop vector** Good open-loop motor performance with minimum configuration
- Open-loop V/Hz control A simple control algorithm that is ideal for parallel motors
- Regenerative Active Front End control mode for harmonic reduction and regeneration

Unidrive SP includes the hardware required to connect to virtually any feedback encoder type, allowing the designer to select the most appropriate technology for the application:

- Incremental Offers a good balance of cost and performance
- SinCos Provides increased position resolution for precision and low-speed applications
- **SSI** Provides absolute position feedback
- **EnDat and HIPERFACE** These encoders transfer position data using a high-speed communications network, often combined with SinCos technology

Add the Extra Features You Need

Snap-in SM option modules allow you to customize the drive to suit your needs. Over 25 different options are available including Fieldbus, Ethernet, I/O, extra feedback devices and automation controllers.

Intelligently Driven

Unidrive SP allows the drive system designer to embed automation and motion control within the drive. This eliminates communication delays that reduce performance while CTNet, a high-performance drive-to-drive network, links the different parts of the system.

Reliability and Innovation

Unidrive SP is designed using a proven development process that prioritizes innovation and reliability. This process has resulted in Control Techniques having a market leading reputation for both product performance and quality.

Global Support

Control Techniques' global network of over 50 Drive Centers located in more than 30 countries, backed by over 30 carefully selected and fully trained international distributors, ensure that service, support and expertise are just around the corner, all around the world. Our engineers are passionate about drives and are able to offer the level of service that you need, from advice on an application problem to providing a complete drive solution design.

Free Standing — Ready-to-Run Large Drives

125 - 2,450hp (90kW - 1.6MW)

Unidrive SP Free Standing drives are supplied in standard NEMA1 enclosures for floor mounting.

The Free Standing can be ordered with input power options to facilitate immediate connection to the power supply and motor.

For more information please refer to the Unidrive SP Free Standing brochure. BRO-USPFS-1107)



SP Modular — Power Rectifier and Inverter Modules 60 - 2,900hp (45kW - 1.9MW)

Unidrive SP Modular offers maximum power system design flexibility. Drive modules can be connected together in a variety of ways to create common DC bus systems, active input systems for returning excess energy to the power

supply and parallelling of drives for high power motors. All drive modules are compact high power density products for easy installation with minimal space requirements.

For more information please refer to the Unidrive SPM brochure.

(BRO-USPSPM-1107)





Unidrive SP Electrical and Mechanical Integration

Unidrive SP enables system designers to reduce costs. Standard features such as integrated EMC filters, through panel mounting and back-up power supply inputs reduce enclosure size and eliminate external components.

Safety as Standard

Unidrive SP's Safe Torque Off (STO) is a functional safety feature which complies with EN/IEC 61800-5-2 SIL 3 and is built into the drive as standard. When the Safe Torque Off function is active, the drive output is disabled with a high degree of integrity.

- Certified by BGIA and TUV
- Allows the drive to become part of the machine safety system
- Reduces user cost in machine safety controller designs that must comply with EN/IEC 62061 up to SIL 3, EN ISO 13849-1 up to PL e, EN 954-1 category 3 and EN 81-1 for elevators
- Eliminates one or more power contactors
- Eliminates need for additional feedback monitoring
- Drive can be powered continuously
- Safe Torque Off can form part of an EN 954-1 Category
 4 system by adding control circuitry.

Back-up Power Supply Inputs for Continuous Operation

24Vdc Input - Control

24Vdc supply allows the Unidrive SP control circuits to remain active when the main power supply is removed. This enables the control portion of the drive (including fieldbus communications, SM option modules and encoders) to remain active and continue to operate.

48-96Vdc Input - Power

Allows the drive power output to control the motor. This feature is often used for emergency back-up situations such as moving elevators to an exit during a power supply failure.









See the SM Option Modules brochure for more detailed information. (BRO-SMOP-1107)



Automation Solutions

Programmable drives offer more compact, higher-performance and lower-cost solutions in machinery automation applications. Over the past 20 years, Control Techniques has pioneered the embedding of programmable automation, motion control and communications features within its Unidrive SP drives.

SM Option Modules

To provide the best possible dynamic motor performance, the following Control Techniques SM option modules contain a high-performance microprocessor that allows the base drive processor to be dedicated to shaft control.

SM-EZMotion

The SM-EZMotion option module and PowerTools Pro

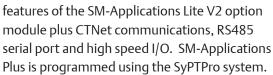


software provide a user-friendly environment for motion programming. The EZMotion approach is ideal for rapid development of motion application solutions.

This option module has four digital inputs and two digital outputs for high-speed I/O operations.

SM-Applications Plus

The SM-Applications Plus option module offers all of the



- Drive-to-drive communications: SM-Applications Plus includes a high-speed drive-to-drive network called CTNet. This network is optimized for intelligent drive systems offering flexible peer-to-peer communications. CTNet has the capability to connect to remote I/O, operator panels, Mentor MP DC drives and PCs.
- High-speed serial port: This option module supports standard protocols such as Modbus (master and follower modes) for connection to external devices such as operator interface panels plus CTSync. CTSync is also standard on SM-Applications Plus and provides the drive clock synchronization with <4µs jitter.
- Inputs/Outputs: SM-Applications Plus has two digital inputs and two digital outputs for high-speed I/O operations such as position capture and actuator firing.

SM-Applications Lite V2

The SM-Applications Lite V2 option module provides



programmable control for standalone drive applications or when the drive is connected to a centralized controller via I/O or Fieldbus. SM-Applications Lite V2 may be programmed using Ladder Logic with SyPTLite or can make

use of the full automation and motion control capabilities contained within SyPTPro, IEC 61131 software.

• Real-time Control: SM Applications Lite V2 provides real-time access to all of the drives' parameters plus access to data from I/O and other drives. The option module uses a high-speed multi-tasking operating system with task update times as low as $250\mu s$. Tasks are synchronized to the drive's own control loops to give you the best possible performance for drive control and motion.

SM-Register

The SM-Register option module is designed to provide



a flexible, high-performance solution for programmable motion requiring high-speed registration features. It is ideal for applications such as printing, packaging and cutting machinery.

Features include:

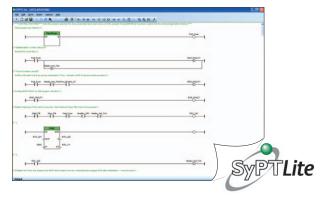
- Motion programming using PLCopen or Control Techniques' Advanced Position Controller (APC)
- Two fully independent registration capture channels
- Storage for 256 events per channel, microseconds apart
- Pattern recognition
- Speeds in excess of 3000ft/min can be handled
- Ability to filter unwanted marks (i.e. splashes, dirt, text, etc)
 - Minimum and/or maximum pulse width
 - Distance from previous edge
- Compensation for registration sensor throughput delay



Automation Software

SyPTLite Onboard Automation Programming

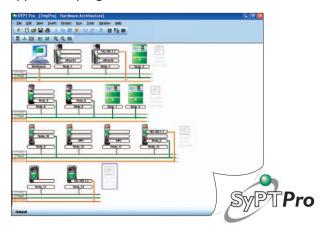
Unidrive SP has a built-in controller programmed using SyPTLite, an easy-to-use Ladder Logic program editor, suitable for replacing relay logic or a micro PLC for simple drive control applications.



SyPTPro Automation Development Environment

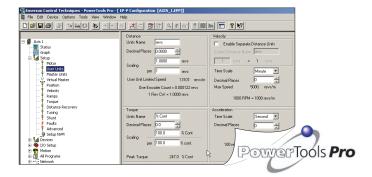
SyPTPro is a full-featured automation development environment that can be used for developing tailored solutions for single or multiple drive applications. The programming environment fully supports three IEC 61131 languages: Function Block, Ladder Logic and Structured Text. Motion control is configured using PLCopen motion language, supporting multiple axes.

CTNet, a high-speed, deterministic drive-to-drive network links the drives, SCADA and I/O together to form networked system, with SyPTPro managing both the application programs and network communications.



PowerTools Pro — Motion Made Easy™

PowerTools Pro is a software program used to develop "Motion Made Easy™" motion control applications and is used when an SM-EZMotion option module is used with the Unidrive SP. PowerTools Pro is used to develop sophisticated motion programs in minutes instead of hours and is ideal for solving a full range of axis and axis-and-a-half servo applications.



SP Control Platform — Stand-alone Unidrive SP Control Module

The SP Control Platform provides all the same functions as a Unidrive SP thus expanding the control flexibility without the ability to run a motor, eliminating redundant power electronics. Applications include:



- Use as a protocol converter between a supervisory control system using one protocol and a drive system using another.
- Adding an extra Unidrive SP to a system to accommodate additional option modules. Additional position feedback devices can also be added to a system in this way.

Unidrive SP, Fast and Easy Integration Flexibility









Terminal Diagram

| RS485 | |
|-------|--|
| Pin# | Function |
| 1 | 120 Ω Termination resistor |
| 2 | RXTX |
| 3 | Isolated 0V |
| 4 | +24V (100mA) |
| 5 | Isolated 0V |
| 6 | TX enable |
| 7 | RX\TX\ |
| 8 | RX\TX\ (if termination resistors are required, link to pin1) |
| Shell | Isolated 0V |

| Control Terminals - Bottom Row | | | | |
|--------------------------------|--------------------|---|--|--|
| Pin# Function | | Description | | |
| 21 | 0V Common | Common for external digital inputs | | |
| 22 | +24Vdc Output | 200mA max user supply | | |
| 23 | 0V Common | Common for external digital inputs | | |
| 24 | Digital I/O 1 | 0 to 24Vdc input, or 1 to 24Vdc, 100mA max output digital I/O | | |
| 25 | Digital I/O 2 | 0 to 24Vdc input, or 1 to 24Vdc, 100mA max output digital I/O | | |
| 26 | Digital I/O 3 | 0 to 24Vdc input, or 1 to 24Vdc, 100mA max output digital I/O | | |
| 27 | Digital Input 4 | 0 to 24Vdc, $6k\Omega$ digital input | | |
| 28 | Digital Input 5 | 0 to 24Vdc, $6k\Omega$ digital input | | |
| 29 | Digital Input 6 | 0 to 24Vdc, $6k\Omega$ digital input | | |
| 30 | 0V Common | Common for external digital inputs | | |
| 31 | Safe Torque Off | 0 to 24Vdc, 8μsec typical/20μsec max sample digital input | | |
| 41 | Status Relay | 240Vac, 2A resistive normally open | | |
| 42 | Status Relay | 240Vac, 2A resistive normally open | | |

| Power - Line/Motor | | |
|--------------------|-------------------|--|
| Pin# | Function | |
| PE | Ground Connection | |
| L1 | Line In | |
| L2 | Line In | |
| L3 | Line In | |
| U | Motor Connection | |
| V | Motor Connection | |
| W | Motor Connection | |
| GND | Motor Ground | |

Connection shown for Size 1 unit





| ٦ | Power - DC Connections | | |
|---|------------------------|----------------|--|
| | Pin# | Function | |
| | 48V | 48Vdc | |
| | -DC | - DC Bus | |
| | +DC | + DC Bus | |
| | BR | Brake Resistor | |
| | GND | Ground | |

Connection shown for size 1 unit Terminal locations may vary based on unit size

| Control Terminals - Top Row | | | |
|-----------------------------|--------------------------|--|--|
| Pin# Function Description | | | |
| 1 | 0V Common | Common for backup power supply | |
| 2 | +24Vdc External Input | 60W, 24Vdc - Backup power supply for control | |
| 3 | 0V Common | Common for external analog signals | |
| 4 | 10Vdc source | 10mA max reference supply | |
| 5 | Analog Input 1+ | $\pm 10 Vdc~100 k\Omega$ - differential analog input, non-inverting input, 16 bit | |
| 6 | Analog Input 1- | $\pm 10 V dc \ 100 k\Omega$ - differential analog input, inverting input, 16 bit | |
| 7 | Analog Input 2 | $\pm 10 V dc$, $100 k\Omega$ or 0-20/ 4-20mA , 200Ω single-ended analog input 10 bit | |
| 8 | Analog Input 3 | $\pm 10Vdc$, $100k\Omega$ or $0-20/$ 4-20mA, 200Ω single-ended analog input 10 bit, motor thermistor input | |
| 9 | Analog Output 1 | ±10Vdc or 0-20 / 4-20mA single-ended analog output, bi-polar, 10 bit | |
| 10 | Analog Output 2 | ±10Vdc or 0-20 / 4-20mA single-ended analog output, bi-polar, 10 bit | |
| 11 | 0V Common | Common for external analog signals | |

| Encoder | | | | |
|---------|-------------------|------------|------------|--|
| Pin# | Signal Quadrature | ABS | Pulse | |
| 1 | A | Cos | F | |
| 2 | A/ | Cosref | F/ | |
| 3 | В | Sin | D, R | |
| 4 | B/ | Sinref | D/, R/ | |
| 5 | Z | Data | Z | |
| 6 | Z/ | Data/ | Z/ | |
| 7 | U | n/c | U | |
| 8 | U/ | n/c | U/ | |
| 9 | V | n/c | V | |
| 10 | V/ | n/c | V/ | |
| 11 | W | Clock | W | |
| 12 | W/ | Clock/ | W/ | |
| 13 | +V | +V | +V | |
| 14 | 0V Common | 0V Common | 0V Common | |
| 15 | Thermistor | Thermistor | Thermistor | |



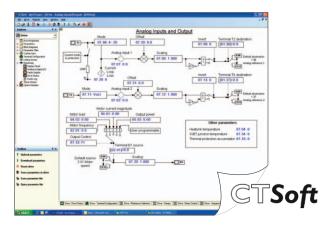
Software and SmartCard Tools for Rapid Project Implementation

Control Techniques FREE software suite makes it easier to access the drive's full feature set. It allows you to optimize the drive tuning, back-up the configuration and set-up communications networks. The software tools can connect using Ethernet, serial ports, USB or CTNet, Control Techniques' drive-to-drive network.

CTSoft Drive Configuration

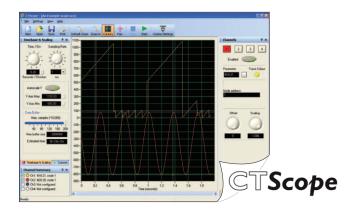
CTSoft is a drive configuration tool for commissioning, optimizing and monitoring Control Techniques drives. It allows you to:

- Use the configuration wizards to commission your drive
- Read, save and load drive configuration settings
- Manage the drive's SmartCard data
- Visualize and modify the configuration with live animated diagrams



CTScope Digital Oscilloscope

CTScope is a full featured 4-channel software oscilloscope for viewing and analyzing changing values within the drive. The time base can be set to give high-speed capture for tuning or for longer term trends. The user interface is based on a traditional oscilloscope, making it familiar and friendly to all engineers worldwide.



Try it! Download CTSoft and CTScope software from www.controltechniques.com



FREE SmartCard Memory Device

The SmartCard is supplied with every Unidrive SP. It can be used to back-up parameter sets and PLC program and copy them from one drive to another.

- Parameter and program storage
- Simplify drive maintenance and commissioning
- Quick set-up for sequential build of machines
- Machine upgrades can be stored on a SmartCard and sent to the customer for installation

SMART(ARI)





Options

The Unidrive SP provides application and system designers with an incredibly flexible drive platform which is easily modified by an extensive range of sophisticated snap-in SM option modules for economical, space saving solutions. SM option modules install easily into any of the three option slots on the Unidrive SP with no tools required. The I/O, feedback, motion control, communication and application modules enable the Unidrive SP to provide an optimized solution to meet your specific application requirements.



| Option | Description | Order Code | | |
|--------------------------------------|---|---|--|--|
| | Cloning and parameter storage card | SMARTCARD ¹ | | |
| | Configuration software | CTSOFT | | |
| | USB 485 communications cable | CT-USB-CABLE | | |
| Base Drive | Keypad to drive cable, 5ft | SP-LCD-485-005 | | |
| Configuration | Keypad to drive cable, 10ft | SP-LCD-485-010 | | |
| and Programming | Keypad to drive cable, 15ft | SP-LCD-485-015 | | |
| Frogramming | Keypad to drive cable, 25ft | SP-LCD-485-025 | | |
| | Keypad to drive cable, 50ft | SP-LCD-485-050 | | |
| | Keypad to drive cable, xxx is cable length in 5ft increments (max length 100ft) | SP-LCD-485-xxx | | |
| | No keypad option | Standard | | |
| | LED keypad (SP size 1-6) | SM-KEYPAD ² | | |
| Operator | LED keypad (SP size 0 only) | KEYPAD-SP0 ² | | |
| Interface | LCD keypad | SM-KEYPAD-PLUS ² | | |
| | Programmable HMI panels | See the Options & Accessories brochure | | |
| | Zero-space brake resistor | Based on Drive | | |
| | E-Stop duty braking resistor | See page 13 | | |
| Power Accessories | Cyclic-duty braking resistor | See the Options & Accessories brochure | | |
| , (6665501.165 | Zero-space EMC filter | Standard | | |
| | External EMC filters | See the Options & Accessories brochure | | |
| | Ladder Logic and Function Blocks | SYPT-LITE | | |
| Applications Programming | IEC 61131-3 (Ladder Logic, Function Block, and text-based) | SYPTPRO | | |
| Software | Motion Made Easy™ programming | POWERTOOLSPRO | | |
| | Systems programming (distributed control) SM-Applications Plus | SM-APPS-PLUS | | |
| Programmable SM Option Modules | Systems programming (centralized control) SM-Applications Lite V2 | SM-APPS-LITE-V2 | | |
| | System programming and registration | SM-REGISTER | | |
| | Dedicated motion control | SM-EZMOTION ⁴ | | |

| 1 C b |
|--|
| 1 Can be ordered separately, but comes standard with Unidrive SP |
| 2 Must be ordered separately |

³ Provides an additional Modbus RTU port (in addition to one on drive)

| is. | | | | |
|--------------------------|---|---|--|--|
| Option Description | | Order Code | | |
| | Modbus RTU follower | Standard | | |
| | Modbus RTU master | SM-APPS-PLUS ³ | | |
| | Modbus RTU master | SM-REGISTER ³ | | |
| | DeviceNet | SM-DEVICENET | | |
| | PROFIBUS DP | SM-PROFIBUS-DP | | |
| | PROFINET | SM-PROFINET | | |
| Communications | Ethernet (Modbus TCP/IP, EtherNet IP) | SM-ETHERNET | | |
| SM Option Modules | INTERBUS-S | SM-INTERBUS | | |
| Wodules | CANopen | SM-CANOPEN | | |
| | CAN Interface | SM-CAN ⁷ | | |
| | Ethernet (EtherCAT) | SM-ETHERCAT | | |
| | SERCOS | SM-SERCOS | | |
| | CTNet, CTSync | SM-APPS-PLUS | | |
| | CTNet, CTSync | SM-REGISTER | | |
| | Universal encoder feedback SM-Universal Encoder Plus | SM-UNI-ENCODER | | |
| Feedback | Incremental encoder input SM-Encoder Plus | SM-ENCODER-PLUS | | |
| SM Option Modules | Incremental encoder input and output SM-Encoder Output Plus | SM-ENCODER-OUT | | |
| | Resolver feedback | SM-RESOLVER | | |
| | Screw terminal connector | SM-ETC | | |
| | Extended analog and digital I/O | SM-I/O-PLUS | | |
| | Extra analog and digital I/O | SM-I/O-LITE | | |
| | Extended I/O | SM-I/O-32 | | |
| I/O SM Option Modules | Extra I/O with Real-Time Clock/ Calendar | SM-I/O-TIMER | | |
| wodules | 120/240 Vac I/O | SM-I/O-120V | | |
| | Double insulated extended I/O | SM-I/O-PELV | | |
| | Remote network I/O | See the Options & Accessories brochure | | |
| | +24 Vdc protected I/O | SM-I/O-24V | | |
| | Safe Torque Off (STO) | Standard | | |
| Safety | High-speed IEC 61800-5-2 functions | SM-SAFETY ⁵ | | |
| Miscellaneous | Conduit entry plates | See the Options & Accessories brochure | | |
| secaneous | IP54 or IP55 cooling fans | (Based on drive) | | |

⁴ Only one of these modules can be used in a Unidrive SP at a time

⁵ Available mid-2011

 $^{6\,\}mbox{Where}\,\mbox{xxx}$ is the length in feet in 5 foot increments up to $100\mbox{ft}$

⁷ Requires an SM-Application module



Internal Dynamic Braking Resistors

During deceleration, the kinetic energy stored in the spinning mass of the motor/load combination is converted to electrical energy which recharges the drive's DC bus. Dynamic braking resistors provide a means of rapidly dissipating that energy so that the drive does not fault from the DC bus over voltage trip. The Ohmic value and power rating of the braking resistor is a function of the application drive type, size and duty cycle.

A zero-space braking resistor is available for heatsink mounting on Unidrive SP frame sizes 0 to 2. These resistors are designed for low-inertia loads commonly used in servo type applications. For higher-inertia loads, the heatsink-mounted resistor may not have enough braking capacity, and a larger external resistor may be required. No additional thermal protection device is required with these heatsink-mounted resistor packages.

| Frame Size | DC Resistance | Power Rating | Order Code |
|---------------|------------------|-----------------|------------------|
| 0 | 70Ω | 50W | SM-HEATSINK-DBR0 |
| 1 | 75Ω | 50W | SM-HEATSINK-DBR1 |
| 2 | 37.5Ω | 100W | SM-HEATSINK-DBR2 |

Drives larger than size 2 do not have this option.

IP54 and IP55 Fan Options

For applications using through-panel mounting, and located in demanding environments, the Unidrive SP can be fitted with optional fans providing either IP54 or IP55 ingress protection ratings. The chart below lists the available fan options.

| Drive Frame Size | IP54 Fan Option Order Code | IP55 Fan Option Order Code |
|---------------------|-------------------------------|-------------------------------|
| 1 | 3024-00 | 3251-3824 |
| 2 | 3024-00 | 3251-3824 |
| 3 | 3251-4024-00 | 3251-1224 |
| 4 | 3251-7824-01 | N/A |
| 5 | Standard | N/A |
| 6 | Standard | N/A |

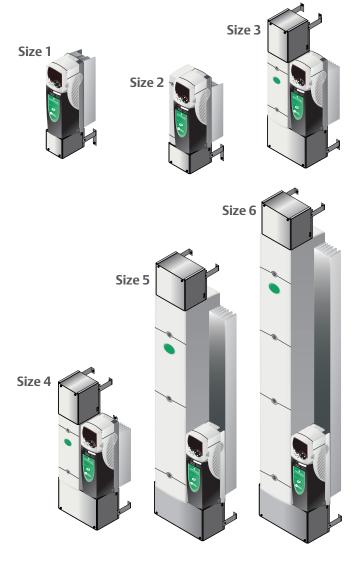
Drives fitted with fan options require field wiring.

Conduit Boxes

Conduit boxes for Unidrive SP (sizes 1 to 6) panel-mount drives.

| Frame Size | Order Code | Overall Dimensions | |
|------------|--------------------------|--------------------|---------------|
| | | Height in (cm) | Width in (cm) |
| Size 1 | C-BOX-S1 | 17.8 (45.2) | 3.94 (10.0) |
| Size 2 | C-BOX-S2 | 17.8 (45.2) | 6.1 (15.5) |
| Size 3 | C-BOX-S3B* C-BOX-S3T* | 21.7 (55.1) | 9.9 (25.1) |
| Size 4 | C-BOX-S4 | 33 (83.9) | 12.2 (31.0) |
| Size 5 | C-BOX-S5 | 45.3 (115) | 12.2 (31.0) |
| Size 6 | C-BOX-S6 | 57.5 (146) | 12.2 (31.0) |

^{*}C-BOX-S3T (top) is only necessary when a DC input power or dynamic braking resistor is required.





Specifications and Dimensions

Specifications

Environment

Ambient Operating 32 to 104 °F (0 to 40 °C)

Temperature 32 to 122 °F (0 to 50 °C) with derating

Cooling method Forced convection

> Humidity 95% maximum non-condensing at 104 °F

(40°C)

Storage Temperature -40 to 122 °F (-40 to 50 °C)

> 0 to 9,900ft (0 to 3000m). Derate 1% per 328ft Altitude

(100m) between 3280ft (1000m) and 9,900ft

(3000m)

Tested in accordance with IEC 60068-2-6, Vibration

2-29, 2-64

In accordance with IEC 60068-2-27 Mechanical Shock

> Enclosure NEMA 1 (IP 20), NEMA 12 (IP 54) through-panel

In compliance with EN 61800-3 and Electromagnetic

Immunity EN 61000-6-2, and complies with

EN61800-3 2nd environment with built-in filter

Electromagnetic In compliance with EN61000-6-3 and 6-4 **Emissions**

EN61000-6-4 when the recommended RFI

filter is used and EMC installation guidelines are

followed

AC Supply Requirements

> Voltage 200 to 240Vac ±10%

380 to 480Vac ±10% 500 to 575Vac ±10%

500 to 690Vac ±10%

Phase 3Ø (SP size Zero: 200 to 240V 1Ø or 3Ø)

2% negative phase sequence (equivalent to 3% Phase Imbalance

voltage imbalance between phases)

Frequency 48 to 65Hz

Input Power Factor Displacement 0.97

Control

Carrier Frequency 3. 4. 6. 8. 12.16kHz - Panel Mount drives

3, 4, 6kHz - Free Standing and SPM drives

Output Frequency 0 to 3000Hz (Open-loop)

0 to 40,000rpm (Closed-loop) **Output Speed**

±0.01% of full scale Frequency Accuracy

Frequency Resolution

10 bit + sign (Qty 2); 16 bit + sign (Qty 1) Analog Input

resolution

Serial 2-wire RS485

4-wire RS232 or RS485 with SM-APPS module Communications

Protocol is ANSI x 3.28-2.5-A4, or Modbus RTU

Baud rate 300 to 115,200

DC injection braking (stopping and holding) and Braking

dynamic braking transistor standard.

Control Power Ride Up to 1 second depending on inertia and decel

Through

Protection

DC Bus 175 / 330 / 435Vdc (approximately Undervoltage Trip 124 / 233 / 307Vac line voltage)

415 / 830 / 990Vdc (approximately 293 / 587 / DC Bus Overvoltage Trip 700Vac line voltage)

225% of drive rated current

MOV Voltage 160 Joules, 1400Vdc clamping (Line to line and

Transient Protection line to ground)

Drive Overload Trip Current overload value is exceeded

Programmable for Normal Duty or Heavy Duty,

open-loop or closed-loop operation

Instantaneous Overcurrent Trip

DC bus ripple threshold exceeded Phase Loss Trip

Overtemperature

Trips

module(s) monitoring

Short Circuit Trip

Ground Fault Trip

Motor Thermal Trip

Protects against output phase to phase fault

Drive heatsink, control board, and option

Protects against output phase to ground fault

Electronically protects the motor from overheating due to loading conditions

Dimensions





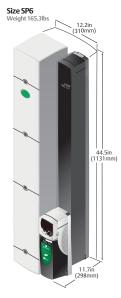














Ratings

| Frame Size | 200-240Vac | Normal Duty | | | Heavy Duty | | | |
|------------|-------------------------------------|----------------------------------|------------------------|---------------------------|----------------------------------|------------------------|---------------------------|--|
| | +/- 10% 3Ø (kW@220V, hp@230V) | Max Continuous Current (A) | Motor Power (hp) | Typical Output (kW) | Max Continuous Current (A) | Motor Power (hp) | Typical Output (kW) | |
| | Order Code | Current (A) | (пр) | (KVV) | Current (A) | (IIP) | (KVV) | |
| | SP0201 | 2.2 | 0.5 | 0.37 | 2.2 | 0.5 | 0.37 | |
| | SP0202 | 3.1 | 0.75 | 0.55 | 3.1 | 0.75 | 0.55 | |
| 0 | SP0203 | 4 | 1 | 0.75 | 4 | 1 | 0.75 | |
| | SP0204 | 5.7 | 1.5 | 1.1 | 5.7 | 1.5 | 1.1 | |
| | SP0205 | 7.5 | 2 | 1.5 | 7.5 | 2 | 1.5 | |
| 1 | SP1201 | 5.2 | 1.5 | 1.1 | 4.3 | 1 | 0.75 | |
| | SP1202 | 6.8 | 2 | 1.5 | 5.8 | 1.5 | 1.1 | |
| | SP1203 | 9.6 | 3 | 2.2 | 7.5 | 2 | 1.5 | |
| | SP1204 | 11 | 3 | 3 | 10.6 | 3 | 2.2 | |
| | SP2201 | 15.5 | 5 | 4 | 12.6 | 3 | 3 | |
| 2 | SP2202 | 22 | 7.5 | 5.5 | 17 | 5 | 4 | |
| | SP2203 | 28 | 10 | 7.5 | 25 | 7.5 | 5.5 | |
| 3 | SP3201 | 42 | 15 | 11 | 31 | 10 | 7.5 | |
| 3 | SP3202 | 54 | 20 | 15 | 42 | 15 | 11 | |
| 4 | SP4201 | 68 | 25 | 18.5 | 56 | 20 | 15 | |
| | SP4202 | 80 | 30 | 22 | 68 | 25 | 18.5 | |
| | SP4203 | 104 | 40 | 30 | 80 | 30 | 20 | |
| 5 | SP5201 | 130 | 50 | 37 | 105 | 40 | 30 | |
| 5 | SP5202 | 154 | 60 | 45 | 130 | 50 | 37 | |

| Frame Size | 380-480Vac +/- 10% 3Ø (kW@400V, hp@460V) | Normal Duty | | | Heavy Duty | | | |
|------------|---|----------------------------------|------------------------|---------------------------|----------------------------------|------------------------|---------------------------|--|
| | | Max Continuous Current (A) | Motor Power (hp) | Typical Output (kW) | Max Continuous Current (A) | Motor Power (hp) | Typical Output (kW) | |
| | Order Code | | | | | | | |
| | SP0401 | 1.3 | 0.5 | 0.37 | 1.3 | 0.5 | 0.37 | |
| | SP0402 | 1.7 | 0.75 | 0.55 | 1.7 | 0.75 | 0.55 | |
| 0 | SP0403 | 2.1 | 1 | 0.75 | 2.1 | 1 | 0.75 | |
| | SP0404 | 3 | 1.5 | 1.1 | 3 | 1.5 | 1.1 | |
| | SP0405 | 4.2 | 2 | 1.5 | 4.2 | 2 | 1.5 | |
| | SP1401 | 2.8 | 1.5 | 1.1 | 2.1 | 1 | 0.75 | |
| | SP1402 | 3.8 | 2 | 1.5 | 3 | 1.5 | 1.1 | |
| 1 | SP1403 | 5 | 3 | 2.2 | 4.2 | 2 | 1.5 | |
| 1 | SP1404 | 6.9 | 5 | 3 | 5.8 | 3 | 2.2 | |
| | SP1405 | 8.8 | 5 | 4 | 7.6 | 5 | 3 | |
| | SP1406 | 11 | 7.5 | 5.5 | 9.5 | 5 | 4 | |
| | SP2401 | 15.3 | 10 | 7.5 | 13 | 7.5 | 5.5 | |
| 2 | SP2402 | 21 | 15 | 11 | 16.5 | 10 | 7.5 | |
| 2 | SP2403 | 29 | 20 | 15 | 25 | 15 | 11 | |
| | SP2404 | 29 | 20 | 15 | 29 | 20 | 15 | |
| | SP3401 | 35 | 25 | 18.5 | 32 | 25 | 15 | |
| 3 | SP3402 | 43 | 30 | 22 | 40 | 30 | 18.5 | |
| | SP3403 | 56 | 40 | 30 | 46 | 30 | 22 | |
| | SP4401 | 68 | 50 | 37 | 60 | 40 | 30 | |
| 4 | SP4402 | 83 | 60 | 45 | 74 | 50 | 37 | |
| | SP4403 | 104 | 75 | 55 | 96 | 75 | 45 | |
| 5 | SP5401 | 138 | 100 | 75 | 124 | 100 | 55 | |
| | SP5402 | 168 | 125 | 90 | 156 | 125 | 75 | |
| | SP6401 | 205 | 150 | 110 | 180 | 150 | 90 | |
| 6 | SP6402 | 236 | 200 | 132 | 210 | 150 | 110 | |

| Frame Size | 200-240Vac +/- 10% 1Ø (kw@220V, hp@230V) | Normal Duty | | | Heavy Duty | | | |
|------------|---|----------------------------------|----------------|---------------------------|----------------------------------|------------------------|---------------------------|--|
| | | Max Continuous Current (A) | Motor Power | Typical Output (kW) | Max Continuous Current (A) | Motor Power (hp) | Typical Output (kW) | |
| | Order Code | Current (A) | (hp) | (KVV) | Current (A) | (up) | (KVV) | |
| 0 | SP0201 | 2.2 | 0.5 | 0.37 | 2.2 | 0.5 | 0.37 | |
| | SP0202 | 3.1 | 0.75 | 0.55 | 3.1 | 0.75 | 0.55 | |
| | SP0203 | 4 | 1 | 0.75 | 4 | 1 | 0.75 | |
| | SP0204 | 5.7 | 1.5 | 1.1 | 5.7 | 1.5 | 1.1 | |
| | SP0205 | 7.5 | 2 | 1.5 | 7.5 | 2 | 1.5 | |

| Frame Size | 500-575Vac | Nori | nal Duty | | Heavy Duty | | | |
|------------|-------------------------------------|-------------------|----------|-------------------|-------------------|-------|-------------------|--|
| | +/- 10% 3Ø (kW@575V, hp@575V) | Max Continuous | Motor | Typical Output | Max Continuous | Motor | Typical Output | |
| | Order Code | Current (A) | (hp) | (kW) | Current (A) | (hp) | (kW) | |
| | SP3501 | 5.4 | 3 | 3 | 4.1 | 2 | 2.2 | |
| 3 | SP3502 | 6.1 | 5 | 4 | 5.4 | 3 | 3 | |
| | SP3503 | 8.4 | 7.5 | 5.5 | 6.1 | 5 | 4 | |
| | SP3504 | 11 | 10 | 7.5 | 9.5 | 7.5 | 5.5 | |
| | SP3505 | 16 | 15 | 11 | 12 | 10 | 7.5 | |
| | SP3506 | 22 | 20 | 15 | 18 | 15 | 11 | |
| | SP3507 | 27 | 25 | 18.5 | 22 | 20 | 15 | |
| | SP4603* | 36 | 30 | 22 | 27 | 25 | 18.5 | |
| 4 | SP4604* | 43 | 40 | 30 | 36 | 30 | 22 | |
| 4 | SP4605* | 52 | 50 | 37 | 43 | 40 | 30 | |
| | SP4606* | 62 | 60 | 45 | 52 | 50 | 37 | |
| 5 | SP5601* | 84 | 75 | 55 | 63 | 60 | 45 | |
| | SP5602* | 99 | 100 | 75 | 85 | 75 | 55 | |
| 6 | SP6601* | 125 | 125 | 90 | 100 | 100 | 75 | |
| | SP6602 | 144 | 150 | 110 | 125 | 125 | 90 | |

| Frame Size | 500-690Vac +/- 10% 3Ø (kW@690V, hp@690V) | Nor | mal Duty | | Heavy Duty | | | |
|------------|---|-------------------|----------|-------------------|-------------------|-------|-------------------|--|
| | | Max Continuous | Motor | Typical Output | Max Continuous | Motor | Typical Output | |
| | Order Code | Current (A) | (hp) | (kW) | Current (A) | (hp) | (kW) | |
| 4 | SP4601 | 22 | 25 | 18.5 | 19 | 20 | 15 | |
| | SP4602 | 27 | 30 | 22 | 22 | 25 | 18.5 | |
| | SP4603 | 36 | 40 | 30 | 27 | 30 | 22 | |
| | SP4604 | 43 | 50 | 37 | 36 | 40 | 30 | |
| | SP4605 | 52 | 60 | 45 | 43 | 50 | 37 | |
| | SP4606 | 62 | 75 | 55 | 52 | 60 | 45 | |
| 5 | SP5601 | 84 | 100 | 75 | 63 | 75 | 55 | |
| | SP5602 | 99 | 125 | 90 | 85 | 100 | 75 | |
| 6 | SP6601 | 125 | 150 | 110 | 100 | 125 | 90 | |
| | SP6602 | 144 | 175 | 132 | 125 | 150 | 110 | |

Notes:

Select model on actual motor full load current. *The same model can be used on a 575V or a 690V supply, and has two different output ratings. For example: At Normal Duty, SP4603 is suitable for a 30hp output motor on a 575V supply and a 40hp output motor on a 690V supply. Can be used on IT supplies - all voltages, Grounded delta supplies - all voltages except 690V

Normal Duty

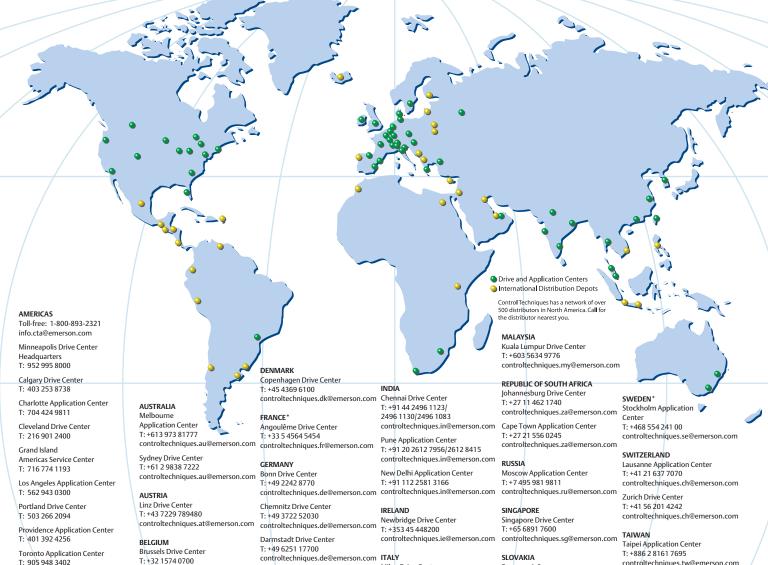
Suitable for most applications, current overload of 110% for 165 seconds is available. Where motor rated current is less than the drive rated continuous current, higher overloads are achieved.

Heavy Dut

Suitable for demanding applications, current overload of 175% for 40 seconds is available for frame size 0 - 5 in closed-loop, 150% for 60 seconds in open-loop, and size 0 single phase current overload is 150% for 60 seconds. For frame size 6 current overload of 150% for 60 seconds is available in closed-loop and 129% for 97 seconds in open-loop. Where the motor rated current is less than the drive rated continuous current higher overloads (200% or greater) are achieved.

Driving Technology...





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